

Existences solution of Nonlinear Functional Integral Equation of Fractional order

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Abstract

In this we study Existences solution of Nonlinear Functional integral equation of fractional order Solution in Banach space of real function defined continuous bounded on an unbounded intervals by using Schunder Fixed point theorem.

Keyword

Fractional order, nonlinear functional integral equation, Fixed point theory, Locally Attractivity, Banach Space.

Introduction

Nonlinear quadratic integral equations appear very often, in many applications of real world problem. For examples, quadratic integral equations are often applicable in the theory of radioactive transfer, kinetic theory of gases, in the theory of neutron transport and in the traffic theory. The theory of integral equations of fractional order has recently received a lot of attention and constitutes a significant branch of nonlinear analysis. Numerous research papers and monographs devoted to differential and integral equations of fractional order have appeared (see [1-3, 5-7, and 9-17]. In recent years, different and integral equation of fractional order have found wide applications in physics mechanics, engineering, electro chemistry, economics and other fields [15,16,19,23,25]. A lot of papers have been devoted to the problem of existence of solutions of nonlinear differential and integral equations of fractional order [1,10-12,14,18,24] However, only a few papers appeared on the existence and properties of solutions of functional integral or differential equations of fractional order on an unbounded interval [6-8,22]. Consider the following functional integral equation order with deviating arguments:

$$x(t) = g(t, x(\eta(t))) + \frac{f(t, x(\beta(t)))}{\Gamma(\alpha)} \int_0^t \frac{h(t, s) u(s, x(\gamma(s)))}{(t-s)^{1-\alpha}} ds, \quad (1.1)$$

Where $t \in R_+ = [0, \infty]$, $\alpha \in (0, 1)$ is a fixed number and $\Gamma(\alpha)$ denotes the gamma function. The aim of this paper is to study the existence of solutions of a nonlinear functional integral equation of fractional order with deviating arguments in the space of real functions, continuous and bounded on an unbounded interval. The technique used here is the measure of non compactness associated with the Scheduler fixed point theorem. Moreover, we will investigate an important property of the solutions which is called the local attractivity of solutions. This property is a generalization of the global attractively of solutions introduced in [17] and is also a variant of the property of asymptotic stability of solutions considered in [2-5, 13, 20, 21]. Eq. (1.1) studied in the paper is a generalization of Chandrasekher type equations [9]. obtained in this paper generalize several ones obtained earlier by many authors.

2. Preliminaries

First we recall a few facts concerning fractional calculus[23]. Denote by $L^1(a, b)$ the space of real functions defined and Lebesgue integrable on the interval (a, b) , which is equipped with the standard norm. Let $x \in L^1(a, b)$ and let $\alpha > 0$ be fixed number[23-31]. The Riemann-Liouville fractional integral of order α of the function $x(t)$ is defined by the formula

$$I^\alpha x(t) = 1/\Gamma(\alpha) \int_a^t \frac{x(s)}{(t-s)^{1-\alpha}} ds, t \in (a, b),$$

Where $\Gamma(\alpha)$ denotes the gamma function. It may be shown that the fractional integral operator I^α transforms the space $L^1(a, b)$ into itself and has some other properties [7, 20, 23, 25].

Next we present some facts concerning the measures of non compactness [5].

Suppose E is a real Banach space with the norm $\| \cdot \|$ and the zero element θ . Denote by $B(x, r)$ the closed ball centered at x and with radius r . We write B_r for the ball $B(\theta, r)$. If X is a subset of E then the symbols \bar{X} and $\text{Conv. } X$ stand for the closure and convex closure of X , respectively[9-23]. Further, let denote the family of all nonempty and bounded subsets of E and \mathcal{N}_E its subfamily consisting of all relatively compact sets.

We define the following notion of measure of non compactness.

Definition 2.1

A mapping $\mu: \mathcal{N}_E \rightarrow R_+$ is said to be a measure of non compactness in the space E if it satisfies the following conditions:

- (i) The family $\ker \mu = \{X \in \mathcal{N}_E: \mu(X) = 0\}$ is nonempty and $\ker \mu = \{X \in \mathcal{N}_E: \mu(X) = 0\}$ is nonempty and $\ker \mu \in \mathcal{N}_E$;
- (ii) $X \in Y \Rightarrow \mu(X) \leq \mu(Y)$;
- (iii) $\mu(\bar{X}) = \mu(\text{Conv} X) = \mu(X)$;
- (iv) $\mu(\lambda X + (1 - \lambda)Y) \leq \lambda \mu(X) + (1 - \lambda)\mu(Y)$ for $\lambda \in [0, 1]$;
- (v) If (X_n) is a sequence of closed sets from \mathcal{N}_E such that $X_{n+1} \in X_n$ for $n=1, 2, 3, \dots$ and if $\lim_{n \rightarrow \infty} \mu(X_n) = 0$ then the set $X_\infty = \bigcap_{n=1}^\infty X_n$ nonempty.

The family $\ker \mu$ defined in axiom (i) is called the kernel of the measure of non compactness μ

Remarks 2.1.

Let us mention that the intersection set X_∞ from (v) is a member of the kernel of the measure of noncompactness μ . Indeed, from the inequality $\mu(X_\infty) \leq \mu(X_n)$ for $n=1, 2, \dots$ we infer that $\mu(X_\infty) = 0$ so $X_\infty \in \ker \mu$. This property of the intersection set X_∞ will be crucial in our study. Further facts concerning measures of noncompactness and their properties may be found in [5, 7].

Now we will work in the Banach space $BC(R_+)$ consisting of all real functions defined, continuous and bounded on R_+ with the norm $\|x\| = \sup\{|x(t)|: t \geq 0\}$

We will use a measure of compactness in the space $BC(R_+)$ which was introduced in [5]. In order to define this measure let us fix a nonempty bounded subset X of the space and a positive number $T \in BC(R_+)$ and a positive number T . For $x \in X$ and $\epsilon \geq 0$ denote by $\omega^T(x, \epsilon)$ the modulus of continuity of the function x on the interval $[0, T]$ i.e.,

$$\omega^T(x, \epsilon) = \sup\{|x(t) - x(s)|: t, s \in [0, T], |t - s| \leq \epsilon\}$$

Further, let us put

$$\begin{aligned} \omega^T(x, \epsilon) &= \sup\{\omega^T(x, \epsilon): x \in X\} \\ \omega_0^T(X) &= \lim_{\epsilon \rightarrow 0} \omega^T(X, \epsilon), \\ \omega_0(X) &= \lim_{T \rightarrow \infty} \omega_0^T(X). \end{aligned}$$

If t is fixed number from R_+ let us denote $X(t) = \{x(t): x \in X\}$ and $\text{diam} X(t) = \sup\{|x(t) - y(t)|: x, y \in X\}$,

Finally consider the function u defined on the family $\mathcal{NBC}(\mathbb{R}_+)$ by the formula

$$\mu(X) = \omega_0(X) + \limsup_{t \rightarrow \infty} \text{diam} X(t). \tag{2.1}$$

It may be shown that the function μ is the measure of non compactness in the space $\text{BC}(\mathbb{R}_+)$. The kernel $\ker \mu$ is the family all nonempty and bounded sets X such that functions belonging to X are locally equicontinuous on \mathbb{R}_+ and the thickness of the bundle formed by functions from X tends to zero at infinity. This property will permit us to characterize solutions of integral equation.

Now let us assume that is non empty subset of the space $\text{BC}(\mathbb{R}_+)$ and Q is open at Defined on Ψ with values in $\text{BC}(\mathbb{R}_+)$ [6-8].

Consider the following operator equation:

$$x(t) = (Qx)(t), t \geq 0 \tag{2.2}$$

Definition 2.2

We say that the solutions of eq.(2.2) are locally attractive if there exists a closed ball $B(X_0, r)$ in the space $\text{BC}(\mathbb{R}_+)$ such that for arbitrary solutions $x = x(t)$ and $y = y(t)$ of eq (2.2) belonging to $B(x_0, r) \cap \Psi$ we have that

$$\lim_{t \rightarrow \infty} (x(t) - y(t)) = 0 \tag{2.3}$$

In the case when the limit (2.3) is uniform with respect to the set $B(x_0, r) \cap \Psi$ i.e. when for each $\epsilon > 0$ there exists $T > 0$ such that

$$|x(t) - y(t)| \leq \epsilon \tag{2.4}$$

For all $x, y \in B(x_0, r) \cap \Psi$ being solutions of eq.(2.2) and for $t \geq T$, we will say that solutions of eq.(2.2) are uniformly locally attractive (or equivalently, that solutions of eq.(2.2) are asymptotically stable

3. Existence Results

In this section we prove the main result of the paper, for that we assume the following assumptions.

(A₁). The function $g: \mathbb{R}_+ * \mathbb{R} \rightarrow \mathbb{R}$ is continuous and there exists a constant $p \geq 0$ such that

$$|g(t, x) - g(t, y)| \leq p|x - y|$$

For any $t \in \mathbb{R}_+$ and for all $x, y \in \mathbb{R}$.

(A₂). The function $f: \mathbb{R}_+ * \mathbb{R} \rightarrow \mathbb{R}$ is continuous and there exists a constant $q \geq 0$ such that

$$|f(t, x) - f(t, y)| \leq q|x - y|$$

For any $t \in \mathbb{R}_+$ and for all $x, y \in \mathbb{R}$.

(A₃). The function $\eta, \beta, \gamma: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ are continuous, and $\eta(t) \rightarrow \infty, \beta(t) \rightarrow \infty$ as $t \rightarrow \infty$.

(A₄). The function $h: \mathbb{R}_+ * \mathbb{R} \rightarrow \mathbb{R}$ is continuous and there exists function $a, b: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ being continuous \mathbb{R}_+ such that $|h(t, s)| \leq a(t)b(s)$ For any $t, s \in \mathbb{R}_+$.

(A₅) The function $u: \mathbb{R}_+ * \mathbb{R} \rightarrow \mathbb{R}$ is continuous moreover, there exists a function $\phi: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ being continuous and nondecreasing on \mathbb{R}_+ and a constant $k \geq 0$ such that $|u(t, x)| \leq k\phi(|x|)$

For any $t \in \mathbb{R}_+$ and for all $x \in \mathbb{R}$.

Now denote by \bar{G} and \bar{F} the following constants: $\bar{G} = \sup\{|g(t, 0)|: t \in \mathbb{R}_+\}$, and

$$\bar{F} = \sup\{|f(t, 0)|: t \in \mathbb{R}_+\}$$

Obviously, $\bar{G}, \bar{F} < \infty$ in view of assumptions (H1) and (H2). Further, let us denote by $\bar{b}(t)$ the function defined on \mathbb{R}_+ in the following way: $\bar{b}(t) = \int_0^t \frac{b(s)}{(t-s)^{1-\alpha}} ds$

It is easily seen that $\bar{b}(t)$ is continuous on \mathbb{R}_+ .

(A₆). The function $\bar{n}: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ defined by the formula $\bar{n}(t) = a(t)\bar{b}(t)$, is bounded on \mathbb{R}_+ and $\lim_{t \rightarrow \infty} \bar{n}(t) = 0$

Keeping in mind, the above assumption we define the following constant: $\bar{N} = \sup\{\bar{n}(t): t \in \mathbb{R}_+\}$

$$N = \bar{N} N \text{ and } M = k \bar{F} \bar{N}.$$

Now, we formulate our last assumption:

(A₇) there exists a positive solution r_0 of the inequality

$$pr + \bar{G} + \frac{1}{\Gamma(\alpha)} [Nr]\varnothing(r) + M\varnothing(r) \leq r, \quad \text{Such that} \quad \left(p + \frac{N\varnothing(r^0)}{\Gamma(\alpha)}\right) < 1.$$

Theorem 3.1. Under assumption (A₁)-(A₇), Eq.(1.1) has at least one solution $x = x(t)$ which belongs to the space $BC(\mathbb{R}_+)$. Moreover, the solution of eq.(1.1) are uniformly locally attractive on \mathbb{R}_+ .

Proof. Consider the operator V defined on the space $BC(\mathbb{R}_+)$ by the formula

$$(V_x)(t) = g\left(t, x(\eta(t))\right) + \frac{f(t, x(\beta(t)))}{r(\alpha)} \int_0^t \frac{h(t, s)u(s, x(\Gamma(s)))}{(t-s)^{1-\alpha}} ds. \tag{3.1}$$

in order to simplify our considerations we represent the operator V in the form

$$(V_x)(t) = (G_x)(t) + (F_x)(t) \tag{3.2}$$

Where

$$\begin{aligned} (G_x)(t) &= g\left(t, x(\eta(t))\right), \\ (F_x)(t) &= f\left(t, x(\beta(t))\right), \\ (U_x)(t) &= \frac{1}{\Gamma(\alpha)} \int_0^t \frac{h(t, s)u(s, x(\Gamma(s)))}{(t-s)^{1-\alpha}} ds \end{aligned}$$

Observe that in view of our assumptions, for any function $x \in BC(\mathbb{R}_+)$ the function G_x and F_x are continuous on \mathbb{R}_+ . We show that the same holds also for the function U_x . To do this fix $T > 0, \epsilon > 0$.

Next assume that $t_1, t_2 \in [0, T]$ are such that $|t_2 - t_1| \leq \epsilon$. Without loss of generality we can assume that $t_1 < t_2$. Then, in view of imposed assumptions, we have

$$\begin{aligned} |(U_x)(t_2) - (U_x)(t_1)| &\leq \frac{1}{\Gamma(\alpha)} \int_0^{t_2} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds - \int_0^{t_1} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds \int_0^{t_1} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds \\ &\quad - \int_0^{t_1} \frac{h(t_1, s)u(s, x(\Gamma(s)))}{(t_1-s)^{1-\alpha}} ds \leq \left|\frac{1}{r(\alpha)}\right| \int_0^{t_2} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds + \int_0^{t_1} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds \\ &\quad - \int_0^{t_1} \frac{h(t_1, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds + \int_0^{t_1} \frac{h(t_1, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds + \int_0^{t_1} \frac{h(t_1, s)u(s, x(\Gamma(s)))}{(t_1-s)^{1-\alpha}} ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} \left| \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} \right| ds + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} \frac{h(t_2, s)u(s, x(\Gamma(s)))}{(t_2-s)^{1-\alpha}} ds \\ &\quad + \frac{1}{r(\alpha)} \int_0^{t_1} |h(t_1, s)| \left| u(s, x(\Gamma(s))) \right| \left| \frac{1}{(t_2-s)^{1-\alpha}} - \frac{1}{(t_1-s)^{1-\alpha}} \right| ds \leq \frac{ka(t_2)}{\Gamma(\alpha)} \int_{t_1}^{t_2} \frac{b(s)\varnothing(|x(Y(s))|)}{(t_2-s)^{1-\alpha}} ds \\ &\quad + \frac{k\omega^T(h, \epsilon)}{\Gamma(\alpha)} \int_0^{t_1} \frac{\varnothing(|x(Y(s))|)}{(t_2-s)^{1-\alpha}} ds + \frac{ka(t_1)}{\Gamma(\alpha)} \int_0^{t_1} b(s)\varnothing(|x(Y(s))|) \left[\frac{1}{(t_1-s)^{1-\alpha}} - \frac{1}{(t_2-s)^{1-\alpha}} \right] ds \\ &\leq \frac{ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha)} \int_{t_1}^{t_2} \frac{1}{(t_2-s)^{1-\alpha}} ds + \frac{ka(t_1)}{\Gamma(\alpha)} \int_0^{t_1} \frac{1}{(t_2-s)^{1-\alpha}} ds + \frac{ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha)} \\ &\times \int_0^{t_1} \left[\frac{1}{(t_1-s)^{1-\alpha}} - \frac{1}{(t_2-s)^{1-\alpha}} \right] ds \leq \frac{ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha+1)} (t_2 - t_1)^\alpha + \frac{ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha+1)} [t_2^\alpha - (t_2 - t_1)^\alpha] \\ &+ \frac{ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha+1)} [t_1^\alpha - t_2^\alpha + (t_2 - t_1)^\alpha] \leq \frac{2ka_T b_T \varnothing(\|x\|)}{\Gamma(\alpha+1)} (t_2 - t_1)^\alpha + \frac{k\omega^T(h, \epsilon)\varnothing(\|x\|)}{\Gamma(\alpha+1)} t_2^\alpha \end{aligned} \tag{3.3}$$

Where we denote

$$\begin{aligned} a_T &= \max\{a(t) : t \in [0, T]\}, b_T = \max\{b(t) : t \in [0, T]\}, \\ \omega^T(h, \epsilon) &= \sup\{|h(t_2, s) - h(t_1, s)| : s, t_1, t_2 \in [0, T], |t_2 - t_1| \leq \epsilon\} \end{aligned}$$

Observe that invoking the uniform continuity of the function $h(t, s)$ on the set $[0, T] \times [0, T]$ we deduce that $\omega^T(h, \epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$. Further, Keeping in mind the estimate(3.3) we obtain

$$\omega^T(U_x \in) \leq \frac{1}{\Gamma(\alpha+1)} [2ka_T b_T \varnothing(\|x\|)] T^\alpha \tag{3.4}$$

Linking inequality (3.4) with the established facts we conclude that the function U_x is continuous on the interval $[0, T]$ for any $T > 0$. This yields the continuity of the function U_x is continuous on the interval $[0, T]$ for any $T > 0$. This yields the continuity of U_x on R_+ .

Finally, combining the continuity of the functions A_x , F_x and U_x we deduce that the function V_x is continuous on R_+ .

Now, taking a function $x \in BC(R_+)$. for an arbitrarily $t \in R_+$. we get

$$\begin{aligned}
 |(V_x)(t)| &\leq |(G_x)(t) + |(F_x)(t)| |(U_x)(t)| \\
 &\leq |g(t, x(\eta(t))) - g(t, 0)| + |g(t, 0)| + \frac{1}{\Gamma(\alpha)} [|f(t, x(\beta(t))) - f(t, 0)|] \int_0^t \frac{|h(t,s)| |u(s, x(\gamma(s)))|}{(t-s)^{1-\alpha}} ds \\
 &\leq p|x(x(\eta(t))) + \bar{G} + \frac{ka(t)[q|x(\beta(t))| + \bar{F}]}{\Gamma(\alpha)} \int_0^t \frac{b(s)\phi(|x(\gamma(s))|)}{(t-s)^{1-\alpha}} ds \\
 &\leq p|x| + \bar{G} + \frac{ka(t)|x|\Phi(|x|)}{\Gamma(\alpha)} \int_0^t \frac{b(s)}{(t-s)^{1-\alpha}} ds + \frac{k\bar{F}a(t)\phi(|x|)}{\Gamma(\alpha)} \int_0^t \frac{b(s)}{(t-s)^{1-\alpha}} ds \\
 &\leq p|x| + \bar{G} + \frac{ka(t)\bar{b}(t)}{\Gamma(\alpha)} |x|\Phi(|x|) + \frac{kfa(t)\bar{b}(t)}{\Gamma(\alpha)} \Phi(|x|) \leq p|x| + \bar{G} + \frac{kq\bar{n}(t)}{\Gamma(\alpha)} \Phi(|x|) \quad (3.5)
 \end{aligned}$$

Now, keeping the assumptions, estimate (3.5) yields

$$\begin{aligned}
 ||V_x|| &\leq p|x| + \bar{G} + \frac{ka\bar{N}}{\Gamma(\alpha)} |x|\Phi(|x|) + \frac{k\bar{F}\bar{N}}{\Gamma(\alpha)} \Phi(|x|) \leq p|x| + \bar{G} + \frac{1}{\Gamma(\alpha)} [N|x|\phi(|x|) + \\
 &M\phi(|x|)] \quad (3.6)
 \end{aligned}$$

Combining this estimate with our assumptions we deduce that there exists a number $r_0 > 0$ such that the operator V transforms the ball B_{r_0} into itself.

Now let us take a nonempty subset $X \in B_{r_0}$ then for $x, y \in X$ and for an arbitrarily fixed $t \in r_+$ we have

$$\begin{aligned}
 |(Vx)(t) - (Vy)(t)| &\leq |g(t, x(\eta(t))) - g(t, y(\eta(t)))| \\
 &+ \left| \frac{f(t, x(\beta(t)))}{\Gamma(\alpha)} \int_0^t \frac{h(t,s)u(s, x(\gamma(s)))}{(t-s)^{1-\alpha}} ds - \frac{f(t, y(\beta(t)))}{\Gamma(\alpha)} \int_0^t \frac{h(t,s)u(s, y(\gamma(s)))}{(t-s)^{1-\alpha}} ds \right| \\
 &\times \int_0^t \frac{h(t,s)u(s, y(\gamma(s)))}{(t-s)^{1-\alpha}} ds \leq p|x(\eta(t)) - y(\eta(t))| + \frac{1}{\Gamma(\alpha)} |f(t, x(\beta(t))) - f(t, y(\beta(t)))| \\
 &\times \int_0^t \frac{h(t,s)u(s, x(\gamma(s)))}{(t-s)^{1-\alpha}} ds + \frac{f(t, y(\beta(t)))}{\Gamma(\alpha)} \int_0^t \frac{h(t,s)u(s, x(\gamma(s))) - u(s, y(\gamma(s)))}{(t-s)^{1-\alpha}} ds \\
 &\leq p|x(\eta(t)) - y(\eta(t))| + \frac{ka(t)|x(\beta(t))|}{\Gamma(\alpha)} \int_0^t \frac{b(s)|u(s, x(\gamma(s)))|}{(t-s)^{1-\alpha}} ds \\
 &+ \frac{a(t)[|f(t, y(\beta(t))) - f(t, 0)| + |f(t, 0)|]}{\Gamma(\alpha)} \int_0^t \frac{b(s)|u(s, x(\gamma(s)))| + u(s, y(\gamma(s)))}{(t-s)^{1-\alpha}} ds \\
 &\leq p|x(\eta(t)) - y(\eta(t))| + \frac{ka(t)|x(\beta(t))| - y(\beta(t))|}{\Gamma(\alpha)} \int_0^t \frac{b(s)\Phi(|x(\gamma(s))|)}{(t-s)^{1-\alpha}} ds \\
 &+ \frac{ka(t)[q|y(\beta(t))| + |f(t, 0)|]}{\Gamma(\alpha)}
 \end{aligned}$$

$$\begin{aligned} & \times \int_0^t \frac{b(s)\Phi(|x(\gamma(s))|) + \Phi(|y(y(s))|)}{(t-s)^{1-\alpha}} ds \leq p|x(\eta(t) - y(\eta(t)))| + \frac{kqa(t)\bar{b}(t)\Phi(r_0)}{\Gamma(\alpha)}|x(\beta(t)) \\ & \quad - y(\beta(t)) \\ & + \frac{2qa(t)\bar{b}(t)}{\Gamma(\alpha)}r_0\Phi r_0 + \frac{2kfa(t)\bar{b}(t)}{\Gamma(\alpha)}\Phi r_0 \leq pdiamX(\eta(t)) + \frac{kqN\Phi(r_0)}{\Gamma(\alpha)}|diamX(\beta(t)) \\ & \quad + \frac{2k\bar{n}(t)}{\Gamma(\alpha)}r_0\Phi r_0 + \frac{2k\bar{n}(t)}{\Gamma(\alpha)}\Phi r_0, \end{aligned}$$

From the above estimate, we derivative the following inequality:

$$Diam(VX)(t) \leq pdiamX(\eta(t)) + \frac{N\Phi(r_0)}{\Gamma(\alpha)}diamX(\beta(t)) + \frac{2k\bar{n}t}{\Gamma(\alpha)}r_0\Phi r_0 + \frac{2k\bar{n}t}{\Gamma(\alpha)}\Phi r_0$$

Hence, from assumption (H6) we get

$$\limsup_{t \rightarrow \infty} diam(VX)(t) \leq k \limsup_{t \rightarrow \infty} diam(X)(t), \tag{3.7}$$

$$\text{Where } k = p + \frac{N\Phi r_0}{\Gamma(\alpha)}$$

Obviously in view of assumption (A₇) we have that k<1.

Further, let us take arbitrary numbers T>0 and ε > 0. Next, fix arbitrarily a function x ∈ X and t₁t₂ ∈ [0, T] such that |t₂ - t₁| ≤ ε with out loss of generally we may assume that t₁ < t₂ then, taking into account our assumptions and using the previously obtained estimate (3.3) we get

$$\begin{aligned} & |(Vx)(t_2) - (Vx)(t_1)| \\ & \leq |(Gx)(t_2) - (Gx)(t_1)| + |(F_X)(t_2)(U_X)(t_2) - (F_X)(t_1)(U_X)(t_2) - (F_X)(t_1)(U_X)(t_1)| \\ & \leq \left| g(t_2, x(\eta(t_2))) - g(t_1, x(\eta(t_1))) \right| \\ & \quad + \frac{|f(t_2, x(\beta(t_2))) - f(t_1, x(\beta(t_1)))|}{\Gamma(\alpha)} \int_0^{t_2} \frac{|h(t_2, s)| |u(\gamma(s))|}{(t_2 - s)^{1-\alpha}} ds \\ & \quad + \frac{|f(t_1, x(\beta(t_1)))|}{\Gamma(\alpha + 1)} [2ka_T b_T \phi(|x|)\epsilon^x + k\omega^T(h, \epsilon)\phi(|x|)T^\alpha] \\ & \leq |g(t_2, x(\eta(t_2))) - g(t_2, x(\eta(t_1)))| + |g(t_2, x(\eta(t_1))) \\ & \quad - g(t_1, x(\eta(t_1)))| + \frac{|f(t_2, x(\beta(t_2))) - f(t_2, x(\beta(t_1)))| + |f(t_2, x(\beta(t_1))) - f(t_1, x(\beta(t_1)))|}{\Gamma(\alpha)} \\ & \times \int_0^{t_2} \frac{ka(t_2)b(s)\phi(|x(\gamma(s))|)}{(t_2 - s)^{1-\alpha}} ds + \frac{|f(t_1, x(\beta(t_1))) - f(t, 0)| + |f(t, 0)|}{\Gamma(\alpha + 1)} [2ka_t b_t \phi(|x|)\epsilon^x + k\omega^T(h, \epsilon)\phi(|x|)T^\alpha] \\ & \leq p|x(\eta(t_2))x(\eta(t_1))|\Psi^T(g, \epsilon) \frac{ka(t_2)[q|x(\beta(t_2)) - x(\beta(t_1))| + \Psi^T(f, \epsilon)]}{\Gamma(\alpha)} \int_0^{t_2} \frac{b(s)\phi(|x(\gamma(s))|)}{(t_2 - s)^{1-\alpha}} ds \\ & \quad + \frac{q|x(\beta(t_1))| + |f(t, 0)|}{\Gamma(\alpha + 1)} [[2ka_t b_t \phi(|x|)\epsilon^x + k\omega^T(h, \epsilon)\phi(|x|)T^\alpha] p\Psi^T(x, v^T(\eta, \epsilon)) + \omega^T(g, \epsilon) \end{aligned}$$

Further let us consider the sequence (Bⁿ_{r₀}), where B¹_{r₀} = ConvV(B¹_{r₀}), B¹_{r₀} = ConvV(B¹_{r₀}) ... Obviously all sets of this sequence are nonempty, bonded, convex and closed. Apart from this we have that Bⁿ⁺¹_{r₀} ⊂ Bⁿ_{r₀} ⊂ B_{r₀} for n = 1,2,3 Thus, keeping in mind that k<1 and taking into account of eq(3.10), we infer that $\lim_{n \rightarrow \infty} \mu(B_{r_0}^n) = 0$ Hence. In view of the axiom (A₆) of definition 2.1, we deduce that the set y = ∩_{n=1}[∞] Bⁿ_{r₀} is nonempty, bounded, convex and closed. Moreover, in the light of Remark 2.1, we have that Y ∈ ker μ. let also observe that the operator V maps the set Y into itself.

Step II :- Now we proves that V is the continuous on the set Y.

Let fix ε > 0 and take the arbitrary function x, y ∈ Y such that ||x - y|| ≤ ε Taking into account the fact that Y ∈ ker μ and the description of sets from ker μ we can find T>0 such that for all x, y ∈ Y and t ≥ T we have that |x(t) - y(t)| ≤ ε.

Now assume that $t \geq T$. then keeping in mind that $x, y \in Y$ and $v: Y \rightarrow Y$, we derive easily the following estimate:

$$|(v_x)(t) - (v_y)(t)| \leq \epsilon$$

Further, take $t \in [0, T]$. Then applying our assumption and evaluating similarly as above, we obtain

$$\begin{aligned} |(Vx)(t) - (Vy)(t)| &\leq p|x(\eta(t)) - y(\eta(t))| + \frac{kqa(t)|x(\beta(t)) - y(\beta(t))|}{\Gamma(\alpha)} \int_0^t \frac{b(s)\phi(|x(Y(s))|)}{(t-s)^{1-\alpha}} ds \\ &+ \frac{a(t)[q|y(\beta(t))| + |f(t, 0)|]}{\Gamma(\alpha)} \int_0^t \frac{b(s)[|u(s, x(y(s)))|]}{(t-s)^{1-\alpha}} ds \\ &\leq p\epsilon + \frac{kqa(t)\bar{b}(t)\Phi(r_0)}{\Gamma(\alpha)}\epsilon + \frac{qa(t)\bar{b}(t)r_0}{\Gamma(\alpha)}\omega^T(u, \epsilon) + \frac{\bar{F}a(t)\bar{b}(t)}{\Gamma(\alpha)}\omega^T(u, \epsilon) \end{aligned} \quad (3.12)$$

Where we denote

$$\omega^T(u, \epsilon) = \sup\{|u(t, x) - u(t, y)| : t \in [0, T], |x|, |y| \leq \epsilon\}.$$

Observe that view of uniform continuity of the function $u(t, x)$

We have that $\omega^T(u, \epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$.

Now linking Eqs. (3.11) and (3.12), we calculated that the operator V is continuous on the set Y .

Finally, taking into account the properties of the set Y and the operator $V: Y \rightarrow Y$ established above and applying the classical Schauder fixed point theorem we infer that the operator V has at least one fixed point $x = x(t)$ in Y . Obviously, the function $x(t)$ is a solution of eq.(1.1). Moreover, the solutions are uniformly locally attractive on R_+ .

4) Application

These results can be applied to the following functional integral equation of fractional order with deviating arguments:

$$x(t) = g(t, x(\eta_1(t)) \dots \dots x(\eta_l(t))) + \frac{f(t, x(\beta_1(t)), \dots, x(\beta_m(t)))}{\Gamma(\alpha)} \int_0^t \frac{u(t, s, x(\gamma_n(s)))}{(t-s)^{1-\alpha}} ds \quad (4.1)$$

Where $t \in R_+$ and α is a fixed number $\alpha \in (0, 1)$.

Assume the following conditions

(B₁) The function $g: R_+ * R^l \rightarrow R$ is continuous and there exists constants $p_i \geq 0 (i = 1, 2, \dots, l)$ such that

$$|g(t, x_1, \dots, x_l) - g(t, y_1, \dots, y_l)| \leq \sum_{i=1}^l p_i |x_i - y_i| \quad (4.2)$$

For all $t \in R_+$ and for all $(x_1, x_2, \dots, x_l), (y_1, y_2, \dots, y_l) \in R$.

(B₂) The function $f: R_+ * R^m \rightarrow R$ is continuous and there exists constants $q_i \geq 0 (i = 1, 2, \dots, m)$ such that

$$|f(t, x_1, \dots, x_m) - g(t, y_1, \dots, y_m)| \leq \sum_{i=1}^m q_i |x_i - y_i| \quad (4.3)$$

(B₃) The function $\eta_i, \beta_i, \gamma_i: R_+ \rightarrow R_+$ are continuous ($i=1, 2, \dots, l; j=1, 2, \dots, m$ and $k=1, 2, \dots, n$).

(B₄) The function $h: R_+ * R_+ \rightarrow R_+$ is continuous and there exists functions $a, b: R_+ \rightarrow R_+$ being continuous on R_+ such that

$$|h(t, s)| \leq a(t)b(s)$$

For any $t, s \in R_+$.

(B₅) The function $u: R_+ * R_+ \rightarrow R_+$ is continuous and Moreover, there exists a function $\Phi: R_+ \rightarrow R_+$ being continuous and non decreasing on R_+ and constants $K_i \geq 0 (i = 1, 2, \dots, n)$ such that

$$|u(t, x_1, \dots, x_n)| \leq \sum_{i=1}^n K_i \Phi(|x_i|) \quad (4.4)$$

For any $t \in R_+$. And for all $s \in R_+$.

Now denote by \bar{G} and \bar{F} , the following constants $\bar{G} = \sup\{|f(t, 0, \dots, 0)| : t \in R_+\}, \bar{F} = \sup\{|f(t, 0, \dots, 0)| : t \in R_+\}$.

Obviously, $\bar{G}\bar{F} < \infty$ in view of assumptions (B₁) and (B₂). Further, let us denote by $\bar{b}(t)$ the function defined on R_+ in the following way:

$$\bar{b}(t) = \int_0^t \frac{b(s)}{(t-s)^{1-\alpha}} ds.$$

It is easily seen that $\bar{b}(t)$ is continuous on R_+ . The function $\bar{n}: R_+ \rightarrow R_+$ defined by the formula $\bar{n}(t) = a(t)\bar{b}(t)$,

Is bounded on R_+ and $\lim_{t \rightarrow \infty} \bar{n}(t) = 0$. Keeping in mind, the above assumption we define the following constants: $\bar{N} = \sup\{\bar{n}(t) : t \in R_+\}$. In order to formulate our last assumption, let us denote $p = \sum_{i=1}^l p_i$, $q = \sum_{i=1}^m q_i$ and $k = \sum_{i=1}^n k_i$, $N = kq\bar{N}$ and $M = \bar{F}\bar{N}$. There exists a positive solution r_0 of the inequality

$$pr + \bar{G} + \frac{1}{\Gamma(\alpha)} [Nr\Phi(r) + M\Phi(r)] \leq r,$$

Such that $(p + \frac{N\Phi(r_0)}{\Gamma(\alpha)}) < 1$.

Under the assumptions (B₁)-(B₅), it is easy to prove that Eq. (4.1) has at least one solution $x=x(t)$ which belongs to the space $BC(R_+)$ and moreover, the solutions are uniformly locally attractive on R_+ .

5. Example

Consider the following nonlinear functional integral equation of fraction order with deviating arguments:

$$x(t) = \frac{t^2 + \text{varctg}(x(t/2))}{4 + 5t^2} + \frac{\cos^2 t + \frac{x(t/3)}{3+t^2}}{\Gamma(1/2)} \int_0^t \frac{se^{-\delta t} \ln\left(1 + \sqrt{\frac{|x(s/4)s}{4}}\right)}{(t-s)^{1/2}} ds, \tag{5.2}$$

Where $t \in R_+$ and v is positive constant. Moreover, δ is fixed natural number.

Notice that the above equation is a special case of Eq.(1.1) if we put $\alpha = \frac{1}{2}$, $\eta(t) = \frac{t}{2}$, $\beta(t) = \frac{t}{3}$, $Y(t) = t/4$ and

$$g(t, x) = \frac{t^2 + \text{varctg}(x(t/2))}{4 + 5t^2}$$

$$f(t, x) = \cos^2 t + \frac{x}{3+t^2},$$

$$h(t, s) = se^{-\delta t}, u(t, x) = \ln(1 + \sqrt{|x|})$$

Obliviously the functions $\eta(t)$, $\beta(t)$ and $\gamma(t)$ satisfy assumption (H3). In fact, we have that the functions $g(t, x)$ and $f(t, x)$ satisfying assumptions (H1) and (H2) with $p=v/4$ and $q=0.3333$ and hence $\bar{G} = 0.2$ and $\bar{F} = 1$.

Further observe that the assumptions (H4) and (H5) are satisfied with $a(t) = e^{-\delta t}$, $b(s) = s$, $\Phi(|x|) = \sqrt{|x|}$ and $k=1$.

Next we check that the assumption (H6) is satisfied, let us notice that the function $\bar{n}(t)$ appearing in that assumption takes the form $\bar{n}(t) = \frac{4}{3}t^{3/2}e^{-\delta t}$. Thus it is easily seen that assumption (h6) is satisfied and hence we get $\bar{N} = \frac{4}{3e}(\frac{1}{\delta})^{3/2}$ and $M = 0.4905(\frac{1}{\delta})^{3/2}$.

Now let us note that the inequality from (H7) has the form

$$\frac{v}{4}r + 0.2 = \frac{1}{\Gamma(1/2)} \left[0.1635 \left(\frac{1}{\delta}\right)^{\frac{3}{2}} \sqrt{r} + 0.4905 \left(\frac{1}{\delta}\right)^{\frac{3}{2}} \sqrt{r} \right] \leq r. \tag{5.2}$$

It is easily seen that the number $r_0=1$ is a solution of inequality (5.2) if we take $v=1$ and $\delta=1$. Obviously the second inequality from assumption (H7) is automatically satisfied in our situation.

Thus on the basis of Theorem 3.1 we conclude that Eq. (5.1) has at least one solution in the space $BC(R_+)$ belonging to the ball B_1 provided $v=1$ and $\delta=1$. Moreover the solutions are uniformly locally attractive on R_+ .

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